

Statistical performance of CO₂ leakage detection using seismic travel time measurements

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Abstract: Monitoring for possible CO₂ leakage is an important part of a safe and effective geological sequestration program. Seismic monitoring has been implemented in several pilot sequestration sites for site characterization and CO₂ leakage detection. This study evaluates the detection power of seismic wave travel time measurements and statistical tests at different CO₂ leakage rate levels. A simplified rock physics model is assumed for monitoring zones at sequestration sites and the effects of leakage-induced changes in pressure and CO₂ saturation on P-wave travel times are modeled. The empirical distributions of detection power using the P-wave travel time for four regions in the permeability-porosity input space at four leakage levels are obtained from the Monte Carlo uncertainty analysis with a stochastic response surface method. The detection power using the P-wave travel time measurements and test alone is generally not high enough, unless the porosity and the permeability of the monitoring zone are high, and/or a long period of time has elapsed since the leakage occurred. For monitoring layers with lower permeability and porosity, measurements from other monitoring techniques will likely be needed to increase the probability that leakage events are detected and addressed in a timely manner. © 2015 Society of Chemical Industry and John Wiley & Sons, Ltd

Keywords: carbon sequestration; leakage detection; seismic monitoring; seismic travel time; statistical power

Introduction

It is estimated that the atmospheric carbon has increased by 240 ± 10 PgC between 1750 and 2011.¹ Most of the increase is due to emissions from fossil fuel combustion and cement production.¹ Geological carbon sequestration in which CO₂ is injected and remains permanently stored in a subsurface formation is considered a promising initial option to slow or reduce global atmospheric CO₂ concentrations.²

Monitoring for possible CO₂ leakage is an important part of a safe and effective geological sequestration

program.³ An overview of available monitoring techniques is provided in the report of the US Department of Energy on Monitoring, Verification, and Accounting of CO₂ Stored in Deep Geologic Formations.³ Monitoring techniques can be categorized into atmospheric monitoring methods, near-surface monitoring methods, and deep-subsurface monitoring methods based on the depth where these techniques are deployed.^{3,4} The performance of near-surface monitoring techniques, including soil CO₂ flux measurements and tracer measurements, has been evaluated by Yang *et al.* using a Bayesian belief

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network approach.^{5–7} Pressure monitoring, a widely used subsurface monitoring technique, has also been extensively studied.^{8–13} A methodology for detecting CO₂ leakage through abandoned wells was developed using pressure and surface-deformation measurements.¹⁴ It is generally found that the individual monitoring techniques studied are unlikely to provide sufficient statistical power for CO₂ leakage detection, so that multiple monitoring techniques may need to be utilized together at a site.^{5,6,8,9}

Seismic methods have been proposed for site characterization and leak detection monitoring. Song *et al.*¹⁵ studied the feasibility of monitoring using a surface wave seismic method and concluded that it is very difficult to detect abnormalities using this method alone. In recent years, the microseismic monitoring technique has been proposed and tested for demonstrating the safety of CO₂ storage at sequestration sites in a cost-effective manner.^{16,17} Bohnhoff *et al.* utilized a passive seismic monitoring network consisting of two arrays of three-component sensors in two monitoring wells to detect CO₂ leakage along monitoring wellbores at a pilot carbon sequestration experiment in the Michigan Basin.^{18,19} Unusual microseismic events were found and believed to be associated with the degassing processes of CO₂ when migrating upward along the monitoring wells. The microseismic monitoring technique has also been carried out at a CO₂-Enhanced Oil Recovery (EOR) pilot project and found useful for CO₂ and CH₄ leakage detection by applying seismological processing schemes to continuous seismic waveform recordings in a two-week period.²⁰ Our study focuses on the performance and detection power of a particular deep-subsurface seismic method, controlled-source seismic measurements above the reservoir caprock.

Seismic monitoring has been commonly applied in oil and gas reservoir characterization and for monitoring changes in reservoir rock properties remotely.²¹ It has also been implemented in several pilot CO₂ sequestration sites, such as the Frio Formation near Houston and the Penn West CO₂-EOR site.^{22–24} Different seismic monitoring methods, including time-lapse 2D or 3D surface seismic surveys, borehole vertical seismic profiling and cross-well seismic monitoring, have been employed at sequestration sites.^{22–25} The seismic attributes that can be measured include seismic velocity, travel time, amplitude and impedance.²³ In our study, predicted changes in

seismic velocity and travel time after CO₂ leakage events occur are considered.

Extensive studies have been undertaken to model CO₂ leakage from sequestration sites. The governing equations controlling these processes are the mass and energy balance equations, which can be solved analytically under simplified assumptions or numerically by space and time discretization. Nordbotten *et al.*²⁶ developed analytical solutions for modeling CO₂ leakage through multiple abandoned wells. There have also been numerical simulators, such as TOUGH2 and STOMP, developed to model multiphase flow in the subsurface.^{27,28} The application of the TOUGH2 simulator in modeling CO₂ leakage has been demonstrated in several studies.^{6, 29–32}

At geological sequestration sites, CO₂ is injected into formations usually more than 1000 m deep. Under the conditions encountered in sequestration reservoirs, CO₂ is in the supercritical fluid phase. To model changes in seismic velocity and seismic travel time after fluid substitution, the Biot-Gassmann equation³³ is commonly used.^{21,34} Gutierrez *et al.*³⁵ studied the effects of CO₂ injection on the seismic velocity of sandstone and confirmed that the Biot-Gassmann substitution theory can be used in modeling changes in the P-wave velocity of sandstone containing supercritical CO₂ and saline water when the distribution of the two fluids in the pore space is accounted for in the calculation.

Uncertainty quantification in modeling CO₂ leakage is crucial in regulatory compliance assessment.³⁶ The uncertainty can be attributed to natural variability within the physical system, incomplete knowledge of model input parameters caused by insufficient or inaccurate site characterization, and simplifications of the physical model.³⁶ Leakage detectability has been assessed through the signal-to-noise ratio using the probabilistic collocation method.³⁷ Oladyshekin *et al.*³⁸ developed a methodology for data-driven uncertainty quantification using polynomial chaos expansion (PCE) and applied it to modeling CO₂ storage in geological reservoirs. The PCE approach, an efficient and flexible uncertainty quantification technique, allows uncertainty analysis of complex and computationally intensive models to be conducted with relatively low computation time.^{12,39} A response surface approach using the multivariate adaptive regression spline (MARS)^{40,41} was employed to estimate wellbore leakage rates of CO₂ and brine from storage reservoirs.⁴² For CO₂ leakage through a fault,

the uncertainties in estimated leakage rates or aquifer chemistry were assessed using polynomial functions as reduced-order models.^{43,44} Reduced order models have also been used to evaluate the impacts of CO₂ leakage on shallow groundwater resources by several authors.^{45,46} Generally applicable problem-solving environments for uncertainty analysis and design exploration (PSUADE),⁴¹ have been developed and integrated into a system-level risk analysis tool.^{42–44} In our study, the uncertainty of the calculated seismic travel time is analyzed using the arbitrary PCE method⁴⁷ combined with Monte Carlo simulation. The PCE model serves as a stochastic response surface for the numerical simulation results from TOUGH2.

The objective of this study is to evaluate the detection power of seismic travel time measurements at different CO₂ leakage rate levels. A simplified rock physics model is assumed for monitoring zones at sequestration sites. Changes in pore pressure and CO₂ saturation at different leakage levels are estimated using the TOUGH2 numerical simulator. The model results are then approximated by the PCE method. Monte Carlo uncertainty analysis is performed for seismic travel time using the Biot-Gassmann equation and the estimated pressure and CO₂ saturation from the fitted PCE models. A methodology for conducting a statistical power analysis is developed and demonstrated based on the ability to distinguish between P-wave travel times with and without pressure and CO₂ saturation changes modeled as a result from CO₂ leakage. The empirical distributions of detection power are obtained at four leakage levels from the Monte Carlo uncertainty analysis.

Modeling changes in seismic travel time

Model set-up

The monitoring zone where the seismic source and receiver are located is modeled as a homogenous layer at a depth of 1 km below the ground surface. The CO₂ would be in the supercritical phase partially saturating the pore space throughout the monitoring zone under the temperature and pressure conditions at this depth. The geometry of the simplified rock physics model for the monitoring zone is illustrated in Figure 1. The lithology type is sandstone with a density of 2600 kg/m³. The lateral extent of the model domain is 10 km and the thickness of the monitoring zone is 50 m. The model domain is discretized with a mesh of 80 × 5(400) grids. The mesh is refined around the leakage point with a grid width of 50 m. The grid width 1 km farther away from the leakage point is 200 m. The CO₂ leakage point is at the center bottom of the monitoring zone. The temperature is constant at 45 °C and the gradient of initial hydrostatic pressure is 0.1 bar/m. Two-phase (supercritical CO₂ and brine) flow has been considered in the model. van Genuchten functions⁴⁸ are adopted to estimate the capillary pressure. The parameters of van Genuchten functions are listed in the Supporting Information.

The initial CO₂ saturation in the pore space is assumed to be zero. The monitoring zone is initially filled with brine with a salinity of 0.15 in weight fraction. The point source of the seismic signal is located at the top of the monitoring zone and the receiver is directly below the source at the bottom of

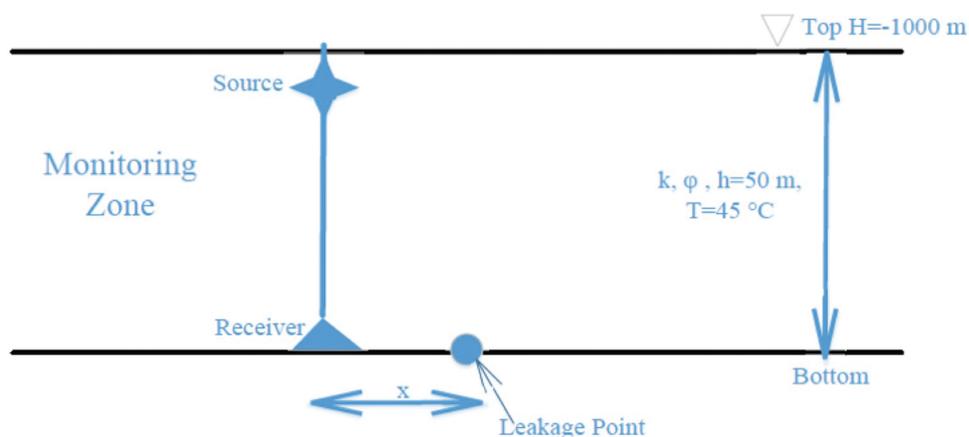


Figure 1. Geometry of the simplified rock physics model for the monitoring zone.

Table 1. Symbols and values for parameters of the modeled monitoring zone.

Parameter	Symbol	Value
Depth below the ground surface (m)	H	1000
Thickness (m)	h	50
Temperature (°C)	T	45
Initial pressure (MPa)	P _{initial}	Uncertain
Permeability (mD)	k	Uncertain
Porosity (%)	φ	Uncertain
Initial CO ₂ saturation	Sg _{initial}	0
Density of rock (kg/m ³)	ρ	2600
Salinity of brine (weight fraction)	S	0.15
CO ₂ leakage rate (tonnes/year)	LR	10, 50, 100, and 150
Distance of monitor from leakage point (m)	x	0 or 500

the monitoring zone. The source and the receiver thus form a vertical line perpendicular to the bottom. The signal recorded is the direct arrival from the top to the bottom of the monitoring zone. The horizontal distance between the receiver and the leakage point is x , which is assumed to be either 0 or 500 m, respectively in this study. The permeability, porosity and initial pressure at the top of the monitoring zone are uncertain input parameters with empirical distributions defined in the section Stochastic response surface method. The symbols and values for parameters of the modeled monitoring zone are summarized in Table 1. Note that the CO₂ storage reservoir and the leakage pathway are not explicitly modeled in this study. It is assumed that 10⁵ tonnes of CO₂ has been injected into the storage reservoir and the migrating CO₂ has reached the center bottom of the monitoring zone through a high permeability conduit in the caprock.

Calculation of seismic velocity and travel time

Based on the laboratory study of rock samples conducted by Wang *et al.*,⁴⁹ changes in seismic velocity are mainly due to changes in pressure and CO₂ saturation in the pore space. The pressure and CO₂ saturation for the no-leakage case and the four leakage rate levels (i.e., small, moderate, large and

very large) are estimated using the TOUGH2/ECO2N module.⁵⁰ The CO₂ leakage rates that correspond to the four leakage levels are 10 tonnes/year, 50 tonnes/year, 100 tonnes/year, and 150 tonnes/year. The small leakage level (i.e., 10 tonnes/year) represents a scenario where 1% of injected CO₂ is leaking from a storage reservoir containing 10⁵ tonnes of CO₂ over 100 years.

Seismic wave velocity in the monitoring zone is estimated using the moduli and density of the rock:

$$V_p = \sqrt{\frac{K_{sat} + \frac{4}{3}\mu}{\rho_{sat}}} \quad (1)$$

$$V_s = \sqrt{\frac{\mu}{\rho_{sat}}} \quad (2)$$

where V_p and V_s are the P- and S-wave velocity; K_{sat} and μ are the bulk and shear moduli of the rock; and ρ_{sat} is the density of the rock.

The bulk modulus of a saturated rock is computed using the Gassmann equation:³³

$$K_{sat} = K_{frame} + \frac{\left(1 - \frac{K_{frame}}{K_{matrix}}\right)^2}{\frac{\phi}{K_{fl}} + \frac{1-\phi}{K_{matrix}} - \frac{K_{frame}}{K_{matrix}^2}} \quad (3)$$

where K_{sat} , K_{frame} , K_{matrix} , and K_{fl} are the bulk moduli of the saturated rock, porous rock frame, mineral matrix and pore fluid, respectively. ϕ is the porosity of the rock as a fraction. The shear modulus is held constant during the fluid substitution in the Gassmann theory. The bulk and shear moduli of the rock frame are estimated using the Hertz-Mindlin contact theory for consolidated rock and the Hashin-Shtrikman bounds.^{51,52} The equations are included in the Supporting Information. The density of the rock is calculated with the volume averaging equation:

$$\rho_{sat} = \phi\rho_{fl} + (1-\phi)\rho_{matrix} \quad (4)$$

where ρ_{fl} and ρ_{matrix} are the density of the fluid phase and the density of the mineral matrix, respectively.

For a formulation and Matlab codes that implement the Gassmann fluid substitution theory, the readers are referred to Kumar.³⁴

Once the gridded fields of seismic velocities are determined, the direct travel time along the vertical wave path from top to bottom is computed as:

$$t = \int_0^h \frac{1}{v} dz \quad (5)$$

where v is the seismic velocity and h is the thickness of the monitoring zone.

Uncertainty quantification and power analysis

The uncertainty of the seismic travel time is estimated using the Monte Carlo method. As the computation time of the TOUGH2 simulation is too large to directly implement the Monte Carlo method with a sufficient sample size, a stochastic response surface using the polynomial chaos expansion is fitted to the TOUGH2 outputs (i.e., pressure and CO₂ saturation), allowing more rapid Monte Carlo evaluation of this surrogate model.

Stochastic response surface method

The stochastic inputs in the uncertainty analysis are permeability, porosity and initial pressure at the top of the monitoring zone. The empirical distributions of permeability and porosity are obtained from the US National Petroleum Council (NPC) database, which contains the raw data for over one thousand reservoirs.⁵³ The initial pressure is sampled independently of the permeability and porosity pairs. While porosity and pressure are expected to exhibit some degree of negative correlation (since formations at greater depth should exhibit somewhat lower porosity and higher pressure), a correlation coefficient of only -0.13 was determined from the NPC database, small enough to yield only a small effect on the subsequent simulation results (especially since it is the change in pressure, rather than the pressure itself that affects observable changes in seismic velocity). A very small correlation coefficient (-0.04) was also determined between permeability and initial pressure. Scatter plots of permeability vs. initial pressure data and porosity vs. initial pressure data in the NPC database are provided in the Supporting Information.

Although the NPC database also contains initial pressure data for reservoirs, they are at various depth and lithology types. In our model setting, the top of the monitoring zone is fixed at a depth of 1 km and

the lithology type of the monitoring zone is sandstone. Therefore, a synthetic dataset for initial pressure at a depth of 1 km and sandstone reservoirs is generated based on the initial pressure data in the NPC database. The distribution of initial pressure is assumed to be a truncated normal with a mean of 9.68 MPa and a standard deviation of 3.94 MPa before the truncation. The lower and upper limits of the truncated normal distribution are 1.93 MPa and 17.42 MPa, respectively. The procedure for generating the synthetic dataset for initial pressure from the truncated normal distribution is shown in the Supporting Information. Figure 2 illustrates the empirical distributions of the three uncertain input parameters. With this approach the empirical distributions of permeability, porosity and initial pressure across all (or, as described below, selected subsets) of the reservoirs in the NPC database are used to prescribe the variation across the parameter space for individual (randomly selected) sites.

The pressure and CO₂ saturation outputs from the TOUGH2 simulation at each leakage level are approximated by PCE on the set of uncertain input parameters $\{\omega_i\}_{i=1}^n$ given by:

$$y = a_0 + \sum_{i=1}^n a_{i1} \Gamma_1(\omega_{i1}) + \sum_{i=1}^n \sum_{i2=1}^{i1} a_{i1i2} \Gamma_2(\omega_{i1}, \omega_{i2}) + \sum_{i=1}^n \sum_{i2=1}^{i1} \sum_{i3=1}^{i2} a_{i1i2i3} \Gamma_3(\omega_{i1}, \omega_{i2}, \omega_{i3}) + \dots \quad (6)$$

where y is an output (either pressure or CO₂ saturation) of the TOUGH2 model; $a_{i1\dots}$ are coefficients to be estimated; and the $\Gamma_p(\omega_{i1}, \dots, \omega_{ip})$ are multidimensional polynomial basis functions that are orthogonal in the input space.

The multidimensional polynomial basis functions $\Gamma_p(\omega_{i1}, \dots, \omega_{ip})$ are constructed using the arbitrary polynomial chaos expansion (aPC) approach of Oladyshkin and Nowak.⁴⁷ The set of aPC basis functions is constructed from the moments of the uncertain input variables. The equations used to construct the aPC basis are provided in the Supporting Information. The aPC approach allows the use of empirical datasets to represent input uncertainties, which avoids errors introduced by fitting standard parametric statistical distributions to empirical datasets. The coefficients ($a_{i1\dots}$) of the polynomial basis can be estimated by the probabilistic collocation method^{54,55} or a statistical regression method.^{36,39}

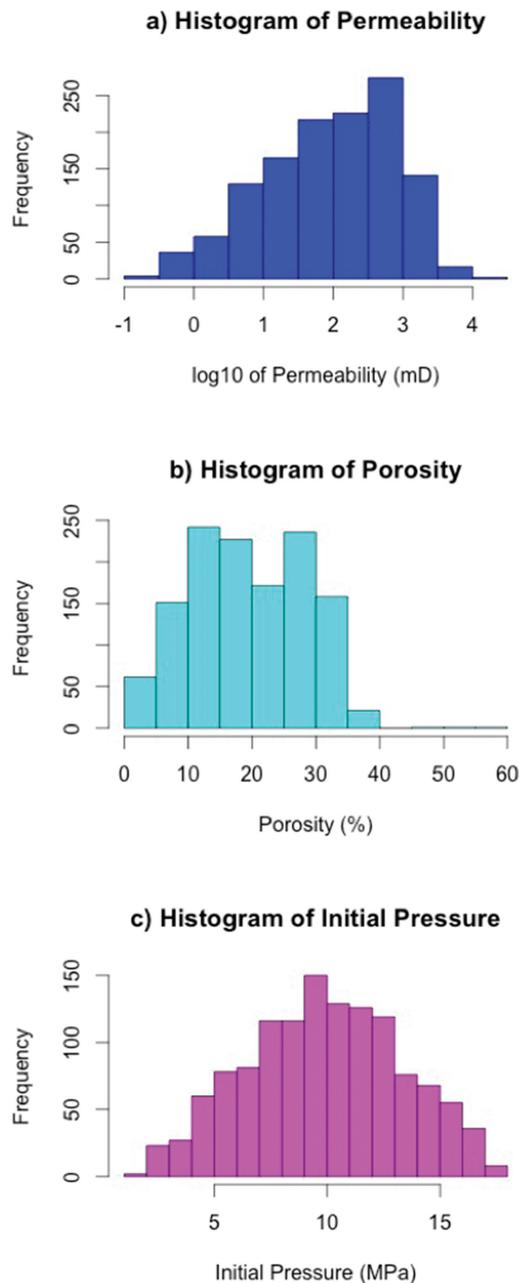


Figure 2. Histograms of stochastic inputs: (a) Permeability; (b) Porosity; and (c) Initial pressure.

In this study, a third-order polynomial expansion function is chosen to approximate the TOUGH2 outputs. As there are three uncertain input parameters ($n = 3$) and the order of the expansion is three ($d = 3$), the total number of terms (M) in the polynomial expansion function is 20, according to the combinatory formula:

$$M = \frac{(n+d)!}{n!d!} \quad (7)$$

The coefficients of the polynomial basis are estimated using the probabilistic collocation method,⁵⁴ which requires evaluating the TOUGH2 model with M different sets of uncertain input parameters $\{\omega_i\}_{i=1}^n$ that are called collocation points. The collocation points are selected from the high probability roots of the $(d+1)$ th (i.e., fourth in this study) order orthogonal polynomial for each uncertain input parameter. At each leakage level, 20 runs of the TOUGH2 model are needed to solve the 20 coefficients in the polynomial expansion function. The PCE models are constructed at each element in the model domain for each output variable (i.e., pressure and CO₂ saturation), resulting in a total of $(80 \times 5) \times 2 = 800$ polynomial functions at each specific time and leakage level.

Monte Carlo uncertainty analysis

Once the PCE models are constructed, the seismic velocity at each element in the model domain can be calculated at a relatively low computational cost, which facilitates Monte Carlo uncertainty analysis. For each set of uncertain input parameters introduced in the section Stochastic response surface method, combined with the fixed parameters in Table 1, the direct seismic travel time from the top to bottom of the formation at locations $x = 0$ m and 500 m are calculated for the no-leakage case and the four leakage levels, at $t = 1, 5, 10$ and 50 years, respectively. The empirical distributions of changes in seismic travel time (Dt) at four leakage levels are obtained by subtracting the travel time for the no-leakage case (T_0) from the travel time at each leakage level ($T_i, i = 1, 4$).

$$Dt = T_i - T_0 \quad (8)$$

where $i = 1$ for small leak, 2 for moderate leak, 3 for large leak and 4 for very large leak

Power analysis

To assess the power of CO₂ leakage detection using seismic travel time, a statistical hypothesis test is assumed to be performed on measured changes in travel time (Dt_m) at each leakage level. The null and alternative hypotheses are given by:

$$H_0 : Dt_m \leq 0 \text{ (no leak)} \quad (9)$$

$$H_1 : Dt_m > 0 \text{ (a leakage event occurs)}$$

As travel time changes of 0.2 to 1.0 ms can be observed using a continuous active-source seismic

monitoring technique,²² the standard deviations of measurement errors of the seismic travel times (T_0 and T_i) are assumed to be 0.2 ms in the hypothesis test, corresponding to a coefficient of variation of 0.2 to 1 in the study by Daley *et al.*²² The distribution of measured seismic travel time is thus assumed to be normal with a mean of the simulated value from the Monte Carlo uncertainty analysis and a standard deviation of 0.2 ms, which is the assumed standard deviation of measurement errors (σ_e). Therefore, the measured changes in seismic travel time (Dt_m) at each leakage level also follow the normal distribution:

$$\begin{aligned} T_{i,m} &\sim N(T_{i,s}, \sigma_e) \\ T_{0,m} &\sim N(T_{0,s}, \sigma_e) \\ Dt_m &= (T_{i,m} - T_{0,m}) \sim N(\mu, \sigma) \end{aligned} \quad (10)$$

where: $\mu = T_{i,s} - T_{0,s}$

$$\sigma = \sqrt{2} \times \sigma_e$$

The hypothesis test (Eqn (9)) tests whether the mean of the measured changes in travel time (Dt_m) is statistically significantly different from zero. If it is, the null hypothesis (i.e., the no-leakage case) is rejected and we conclude that the measured travel times provide sufficient evidence of a leakage event. The critical value of Dt_m for the hypothesis test is chosen to be $Dt_{cri} = 2\sigma$, corresponding to a significance level of about 0.02 for the test of hypothesis. The power of the hypothesis test for CO₂ leakage detection is computed as the probability that Dt_m is larger than Dt_{cri} when a leakage event occurs (at each of the four leakage levels). Note that a group of measurements of changes in seismic travel time is assumed to be made, after which the mean of the observed values will be compared to Dt_{cri} . However, since these measurements (and their errors with respect to leakage effects and inference) are expected to be highly correlated, the effective sample size is conservatively assumed to be one.

Results and discussion

Predicted seismic velocity in model domain

Seismic velocities, including the P-wave velocity and the S-wave velocity, at each element in the model domain are calculated using the predicted pressure

and CO₂ saturation values from the PCE models, combined with the Biot-Gassmann model for fluid substitution introduced in the section Calculation of seismic velocity and travel time. Figure 3 shows the model results for the no-leakage case and the moderate leakage level at $t = 10$ year. In this figure, the values of the three uncertain input parameters are as follows: permeability = 100 mD, porosity = 15% and initial pressure = 9.5 MPa. The results at $t = 1, 5,$ and 50 year and at different leakage levels are shown in the Supporting Information.

The velocity of the P-wave decreases by about 7.5% around the leakage point at the moderate leakage level after 10 years of leakage. The effect of the decreased P-wave velocity propagates upwards in the center towards the top of the monitoring zone. For the areas at the bottom of the monitoring zone but far away from the center, the P-wave velocity decreases by about 3.7%. Discontinuities in the P-wave velocity occur at distances beyond 1000 m from the point of leakage; however these do not influence the estimates that follow, as the estimates are made for monitors located at $x = 0$ or $x = 500$ m from the leakage point. In general, as the leakage level and time increases, the drop in the P-wave velocity gets larger and affects larger areas in the monitoring zone. The decrease in P-wave velocity is the competing effects of pore pressure and CO₂ saturation increase after CO₂ leakage occurs in the monitoring zone.

The S-wave velocity changes little, increasing slightly around the leakage point by about 0.8% at the moderate leakage level after 10 years of leakage. The maximum increase in S-wave velocity at all the leakage levels considered in this study is about 1% (at the very large leakage level). The effect of CO₂ saturation on the changes in S-wave velocity is caused mainly by the change in the density of the pore fluid. The shear modulus of the rock is not affected by CO₂ saturation because the shear modulus of fluids is zero. Pore pressure has an impact on both the shear modulus of the rock and the density of the pore fluid. As the changes in S-wave velocities are too small to serve as a basis for leakage detection, the S-wave travel time is excluded from further analysis.

Detection power using P-wave travel time

Monte Carlo uncertainty analysis is performed for the P-wave travel time along a vertical wave path from the top to the bottom of the formation (Figure 1) at

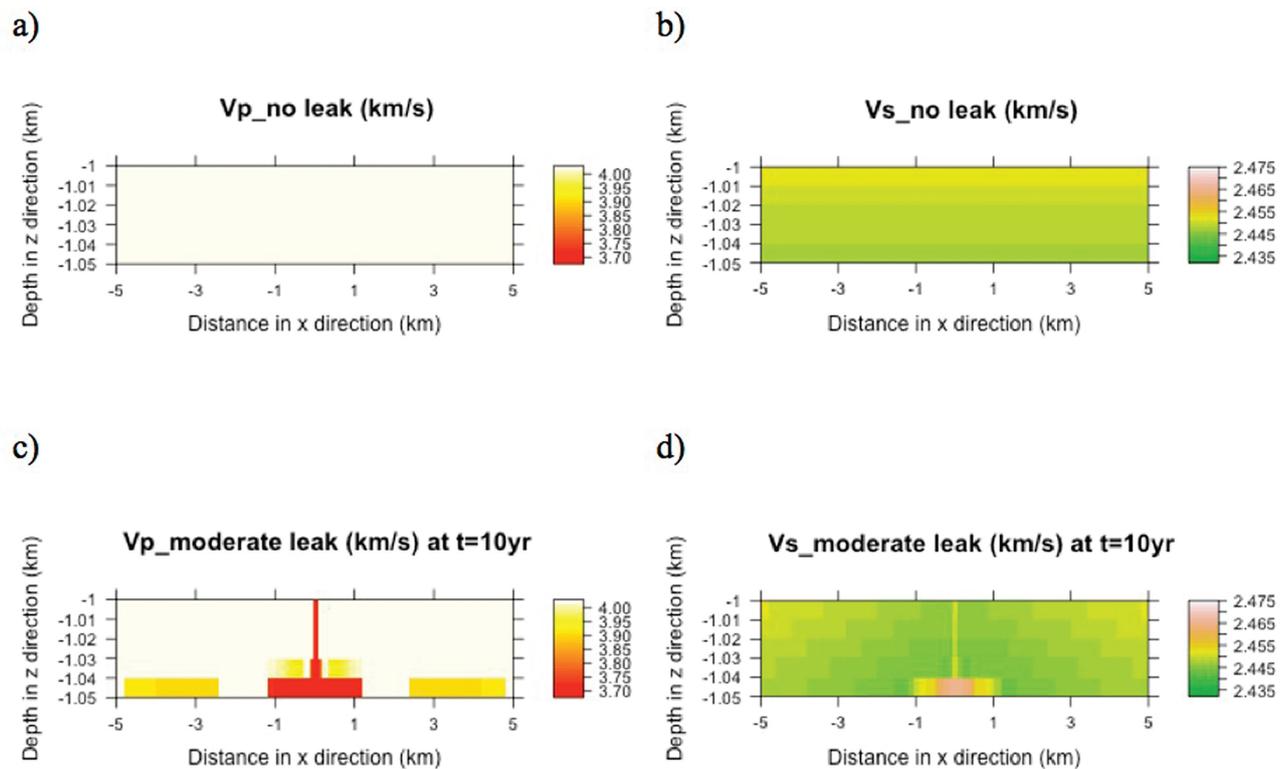


Figure 3. Sample model results of P-wave (a and c) and S-wave (b and d) seismic velocities for the no-leakage case (a and b) and the moderate leakage level (c and d) at $t = 10$ year ($k = 100$ mD, $\phi = 15\%$, $P_{initial} = 9.5$ MPa).

locations $x = 0$ and 500 m respectively, from the point of leakage. The input parameter space is divided into four regions based on permeability and porosity ranges, as in practice, the permeability and porosity ranges of the monitoring zone could be known in advance by site characterization. Four primary groups are identified in the input permeability-porosity space from the NPC database, denoted by different colors in Figure 4. In addition, initial pore pressures are sampled independently for each case from the assumed truncated normal distribution shown in Figure 2(c). The group of points in red represents inputs with low porosity. The groups of points in green, orange and purple represent inputs with relatively high porosity, and with low, moderate and high permeability, respectively. Figures 5–7 show the resulting computed empirical cumulative distribution function (CDF) of detection power using the P-wave travel time at the location $x = 0$ m (center of the monitoring zone) for the four regions in the input permeability-porosity space at $t = 5$, 10 and 50 year, respectively. The results for the location $x = 500$ m and those at $t = 1$ year are shown in the Supporting Information.

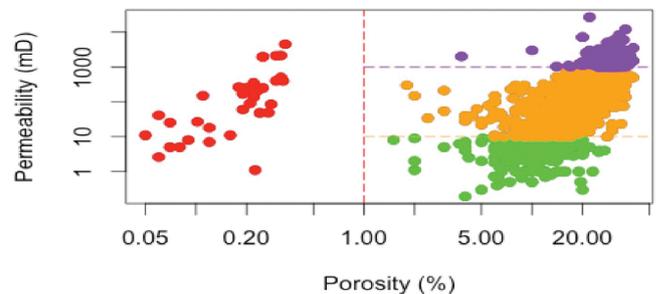


Figure 4. Scatter plot of permeability vs. porosity input parameters used in the Monte Carlo simulation. Each point represents an observation in the US National Petroleum Council (NPC) database. The observations are classified into four regions of the parameter space as indicated by color.

It is evident that the detection power of the test of hypothesis for decreases in the P-wave travel time differs for different regions of the permeability – porosity input space. The P-wave travel time test exhibits good power for CO₂ leakage detection if the permeability and porosity of the monitoring zone are

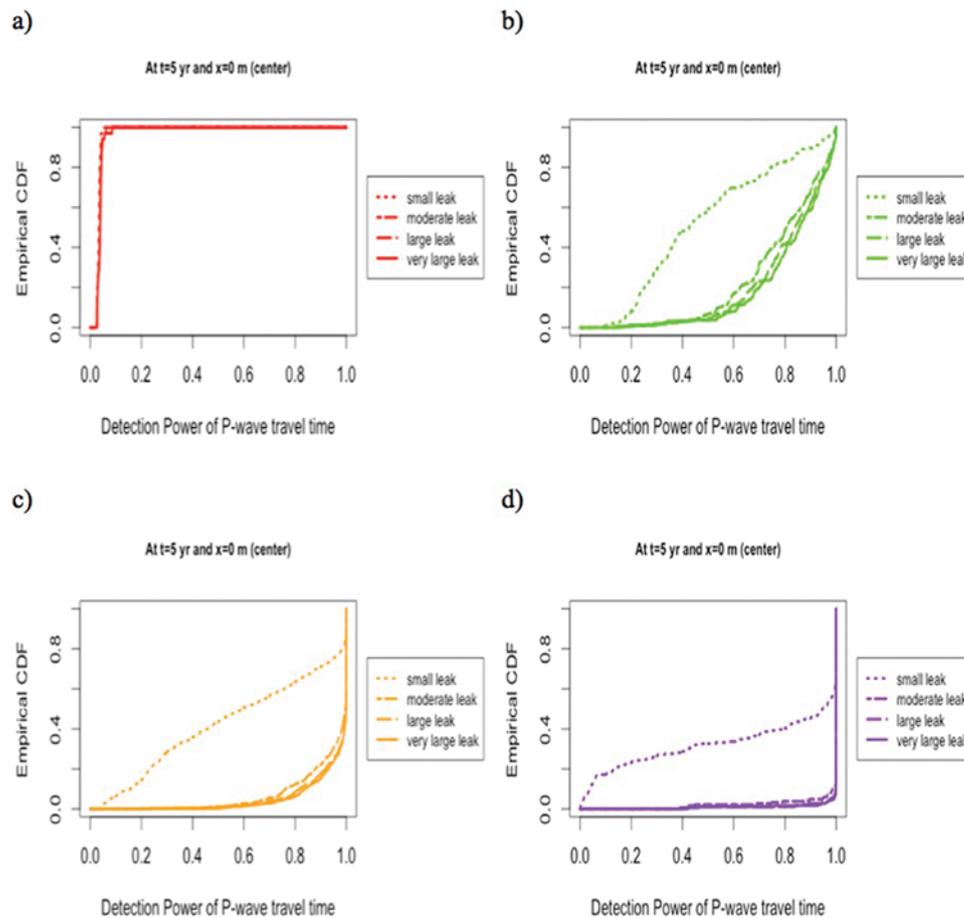


Figure 5. Empirical CDF of detection power of P-wave travel time test of hypothesis (Eqn (9), at significance level $\alpha = 0.02$) at four leakage levels, $t = 5$ year, $x = 0$ m and at (a) low porosity region (red points in Fig. 4); (b) high porosity and low permeability region (green points in Fig. 4); (c) high porosity and moderate permeability region (orange points in Fig. 4); and (d) high porosity and high permeability region (purple points in Fig. 4).

relatively high (purple curves in Figures 5–7(d)). The detection power using the P-wave travel time test is very low for monitoring zones with low porosity, no matter the value of the permeability value (red curves in Figures 5–7(a)). For monitoring zones with porosity larger than 1% (green, orange, and purple regions in Figure 4), the detection power using the P-wave travel time test is generally higher for a high permeability formation than for a low permeability layer. The detection power increases with increasing time since the leakage occurs. For example, comparing Figure 5(c) to Figure 7(c), the probability of achieving a detection power larger than 0.8 at the small leakage level increases from 0.4 (at $t = 5$ year) to about 0.82 (at $t = 50$ year) if the permeability and porosity ranges

of the monitoring zone fall into the orange region in Figure 4. As shown in Figure 7(d), high detection power using the P-wave travel time test can be achieved for monitoring zones with high permeability at $t = 50$ year. Comparing the results at $x = 0$ m to those at $x = 500$ m, it is seen that the detection power is higher at the location closer to the leakage point ($x = 0$ m) than at the location farther away ($x = 500$ m). The detection power does not change much for different CO₂ leakage levels at the location $x = 0$ m. However, at the location $x = 500$ m, a higher leakage level is necessary before a detection based on the seismic wave velocity is likely to occur.

The expected detection power using the P-wave travel time test of hypothesis for different regions of

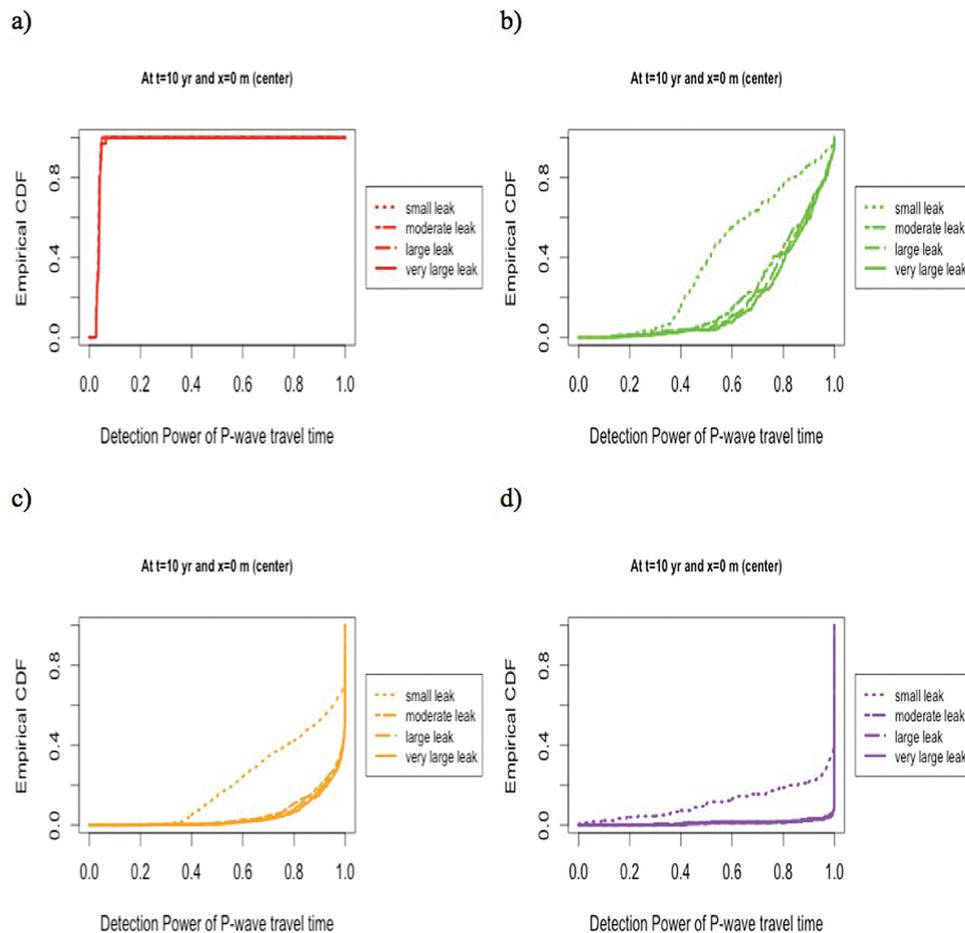


Figure 6. Empirical CDF of detection power of P-wave travel time test of hypothesis (Eqn (9), at significance level $\alpha = 0.02$) at four leakage levels, $t = 10$ year, $x = 0$ m and at (a) low porosity region (red points in Fig. 4); (b) high porosity and low permeability region (green points in Fig. 4); (c) high porosity and moderate permeability region (orange points in Fig. 4); and (d) high porosity and high permeability region (purple points in Fig. 4).

the permeability and porosity input space at the location $x = 0$ m and at four leakage levels is illustrated in Figure 8 as a function of time since the leakage occurs. Under the assumed uncertainty in the input parameters and the specified geometry of the rock physics model, the detection power remains low, especially for a small or moderate leak, until after five years of leakage has occurred. For monitoring zones with low porosity (red lines in Figure 8), the expected power for detecting small leakage events is very low regardless of time. For small leakage rates at high porosity sites, higher permeability does lead to increased power, though at higher leakage rates these differences are no longer apparent, since high power is achieved in all cases with high porosity

(irrespective of permeability) after five or more years of leakage.

Discussion

The conceptual model used in our analysis for the subsurface seismic monitoring zone is highly simplified, assuming homogeneous porosity and permeability, a single fixed leakage source, and known spatial dimensions; with variation across sites captured in the distribution of reported average (or, representative) porosity and permeability. This approach was taken to provide a relatively simple and tractable basis upon which a framework for power analysis could be built and demonstrated, involving: (i) simulation of

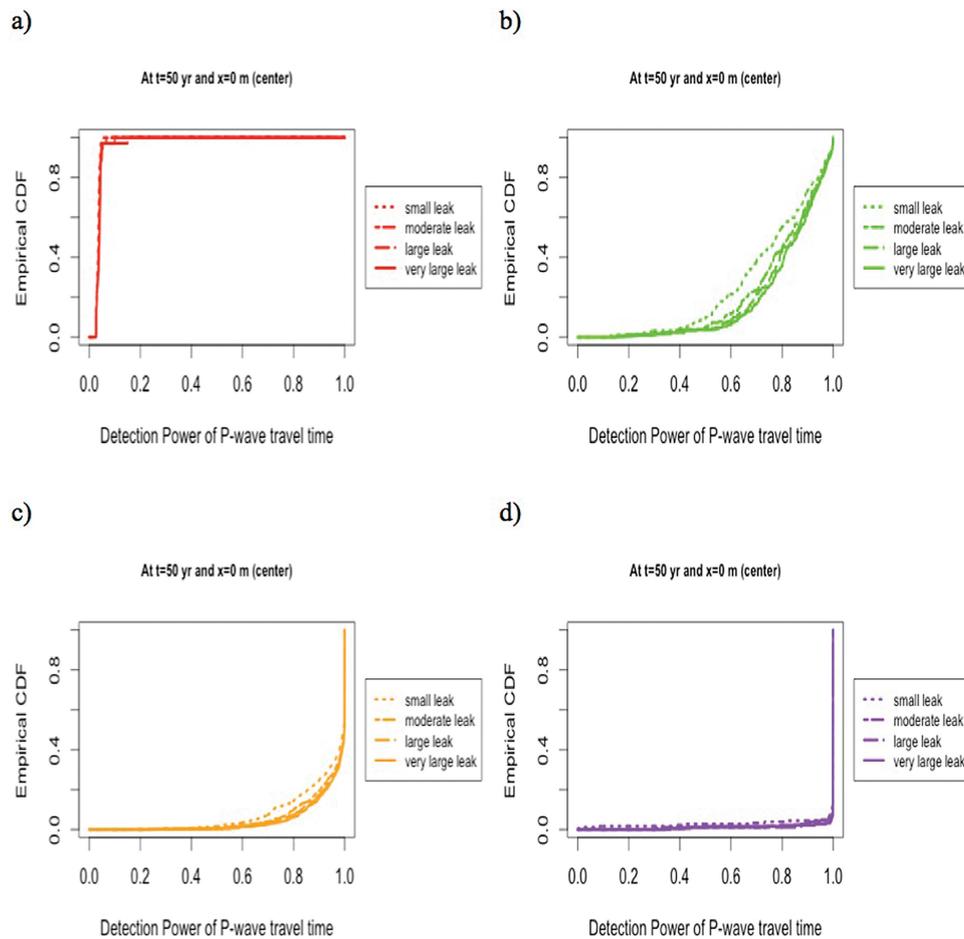


Figure 7. Empirical CDF of detection power of P-wave travel time test of hypothesis (Eqn (9), at significance level $\alpha = 0.02$) at four leakage levels, $t = 50$ year, $x = 0$ m and at (a) low porosity region (red points in Fig. 4); (b) high porosity and low permeability region (green points in Fig. 4); (c) high porosity and moderate permeability region (orange points in Fig. 4); and (d) high porosity and high permeability region (purple points in Fig. 4).

the pressure and CO₂ saturation response to leakage in the monitoring zone; (ii) calculation of the resulting effect on seismic wave velocities; (iii) consideration of the effect of monitoring measurement error; and (iv) evaluation of the resulting statistical distribution of monitored seismic wave velocities under the null (no leakage) and alternative (leakage of different magnitudes) hypotheses. While we believe that the results for different types of reservoirs (colors in Figures 4–8) provide useful initial insights into which are likely to have the potential for effective seismic wave monitoring for leak detection, it is the development of this overall conceptual framework that is the

major contribution of the paper. When applied at actual sites, the framework will require consideration of reservoir heterogeneity, with spatially varying (and uncertain) distributions of porosity, permeability and other features at the site. Methods to simulate uncertain subsurface spatial fields conditioned on partial observations of permeability and other measurements are available using approaches that rely on knowledge of subsurface processes and statistical techniques such as Sequential Gaussian Simulation.^{56–58} We look forward to using methods such as these to evaluate seismic monitoring and other leak detection methods at a test site at some time in the future.

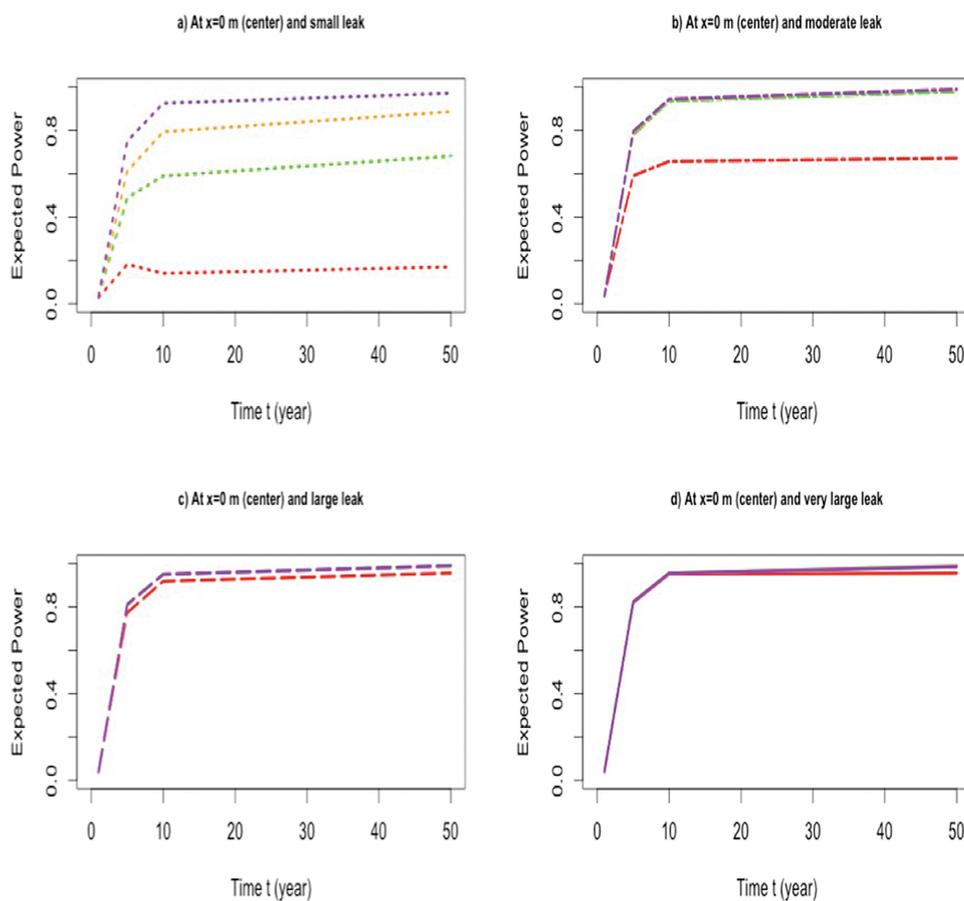


Figure 8. Expected detection power of P-wave travel time test of hypothesis (Eqn (9), at significance level $\alpha = 0.02$) as a function of time since leakage for four regions of the permeability and porosity input space (the red, green, orange and purple regions in Fig. 4, denoted by colored lines in Fig. 8), at the location $x = 0$ m and at (a) small leakage level; (b) moderate leakage level; (c) large leakage level; and (d) very large leakage level.

Conclusions

In this work, the power of CO₂ leakage detection using a statistical analysis and test of P-wave travel times is assessed with a simplified rock physics model for the monitoring zone. The empirical distributions of detection power using the P-wave travel time for four regions in the permeability-porosity input space at four leakage levels are obtained from the Monte Carlo uncertainty analysis with a stochastic response surface method. For a reservoir with intermediate values of porosity, permeability and initial pressure, the model results predict that the P-wave velocity decreases by about 7.5% around the leakage point 10 years after the initiation of a moderate leakage rate. The detection power using the P-wave travel time

measurements and test alone is generally not high enough for small leakage events, unless the porosity and the permeability of the monitoring zone are high, and/or a long period of time has elapsed since the leakage occurred. The results indicate that there is an advantage to choosing a monitoring zone with high porosity and high permeability for the purpose of monitoring CO₂ leakage with seismic wave velocity detection. The detection power is higher when the leak occurs near the location of the monitoring system, suggesting the possible need for multiple monitoring locations when the reservoir and the monitoring zone are large. As the likely pathways for concentrated CO₂ leakage at sequestration sites include abandoned wells and faults, the seismic monitoring equipment may be most effectively

deployed along the abandoned wells or above the faults (if any are present). As the sole measurement of the P-wave travel time cannot provide sufficient power for CO₂ leakage detection in many cases, measurements from other monitoring techniques, such as pressure monitoring and near-surface monitoring will likely need to be combined at sequestration sites to increase the probability that leakage events are detected and addressed in a timely manner.

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